Sub- EC-II Lesson Plan Sem-sth Name of Faculty - Miss Mitalee Behera

Sub Code - EETSOI

## EC-II, 5th electrical

SL.	MONTH	UNIT/	Lesson Plan		
NO		MODULE	COURSE TO BE COVERED	TOTAL	REMARKS
01.	September	UNIT-1	ALTERNATOR:	CLASSES	
			1.1. Types of alternator and their constructional	14	
			features. 1.2. Basic working principle of alternator		
			and the relation between speed and frequency.		
			1.3. Terminology in armature winding and		
			expressions for winding factors (Pitch factor,		
			Distribution factor). 1.4. Explain harmonics, its		
			causes and impact on winding factor, 1.5, E.M.F.		
			equation of alternator. (Solve numerical problems).		
			1.6. Explain Armature reaction and its effect on		
			emf at different power factor of load. 1.7. The		
			vector diagram of loaded alternator. (Solve		
			numerical problems) 1.8. Testing of alternator		
			(Solve numerical problems) 1.8.1. Open circuit test 1.8.2. Short circuit test. 1.9. Determination of		
			voltage regulation of Alternator by direct loading		
			and synchronous impedance method. (Solve	5	
			numerical problems) 1.10. Parallel operation of	f	
			alternator using synchro-scope and dark & brigh	t	
			lamp method. 1.11. Explain distribution of load b	V	
			parallel connected alternators.		
02.	October	UNIT-2	SYNCHRONOUS MOTOR:	08	
			2.1. Constructional feature of Synchronous Moto	r.	
			2.2. Principles of operation, concept of load ang	le	
			2.3. Derive torque, power developed. 2.4. Effect		
			varying load with constant excitation. 2.5. Effect		
			varying excitation with constant load. 2.6. Pow	er	
			angle characteristics of cylindrical rotor motor. 2		
			Explain effect of excitation on Armature curre		
			and power factor. 2.8. Hunting in Synchrono		
			Motor. 2.9. Function of Damper Bars		
			synchronous motor and generator. 2.10. Descr		
			method of starting of Synchronous motor. 2		
			State application of synchronous motor.		
03.	October	UNIT-3	THREE PHASE INDUCTION MOTOR:	14	
			3.1. Production of rotating magnetic field.		
			Constructional feature of Squirrel cage and Slip		
			induction motors. 3.3. Working principles		
			operation of 3-phase Induction motor. 3.4. De		
			slip speed, slip and establish the relation of		
			with rotor quantities. 3.5. Derive expression		
			torque during starting and running conditions		
			derive conditions for maximum torque. (	solve	
			numerical problems) 3.6. Torqu	e-slip	
			characteristics. 3.7. Derive relation between		

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			load torque and starting torque etc. (solve numerical problems) 3.8. Establish the relations between Rotor Copper loss, Rotor output and Gross Torque and relationship of slip with rotor copper loss. (solve numerical problems) 3.9. Methods of starting and different types of starters used for three phase Induction motor. 3.10. Explain speed control by Voltage Control, Rotor resistance control, Pole changing, frequency control methods. 3.11. Plugging as applicable to three phase induction motor. 3.12. Describe different types of motor enclosures. 3.13. Explain principle of		
4.	November	UNIT-4	Induction Generator and state its applications.	00	
	, to telliber	J1111-4	SINGLE PHASE INDUCTION MOTOR:	08	
05.	December	UNIT-5	4.1. Explain Ferrari's principle. 4.2. Explain double revolving field theory and Cross-field theory to analyze starting torque of 1-phase induction motor. 4.3. Explain Working principle, Torque speed characteristics, performance characteristics and application of following single phase motors. 4.3.1. Split phase motor. 4.3.2. Capacitor Start motor. 4.3.3. Capacitor start, capacitor run motor. 4.3.4. Permanent capacitor type motor. 4.3.5. Shaded pole motor. 4.4. Explain the method to change the direction of rotation of above motors.  COMMUTATOR MOTORS:  5.1. Construction, working principle, running characteristic and application of single phase series motor. 5.2. Construction, working principle and application of Universal motors. 5.3. Working principle of Repulsion start Motor, Repulsion start	06	
			Induction run motor, Repulsion Induction motor.		
06.	December	UNIT-6	SPECIAL ELECTRICAL MACHINE:  6.1. Principle of Stepper motor. 6.2. Classification of Stepper motor. 6.3. Principle of variable reluctant stepper motor. 6.4. Principle of Permanent magnet stepper motor. 6.5. Principle of hybrid stepper motor. 6.6. Applications of Stepper motor.		
07	January	UNIT-7	THREE PHASE TRANSFORMERS:  7.1. Explain Grouping of winding, Advantages. 7.2. Explain parallel operation of the three phase transformers. 7.3. Explain tap changer (On/Off load tap changing) 7.4. Maintenance Schedule of Power Transformers.		